

Algoritmo con profundidad limitada (Depth-limited search - DLS)

Agenda

$[\emptyset]$						
$[G_B^1$	A_B^1	S_B^1	$\mathcal{H}_B^1]$			
$[G_B^1$	A_B^1	S_B^1	R_H^2	J_H^2	$\mathcal{V}_H^2]$	
$[G_B^1$	A_B^1	S_B^1	R_H^2	$\mathcal{X}_H^2]$		
$[G_B^1$	A_B^1	S_B^1	R_H^2	$\mathcal{D}_J^3]$		
$[G_B^1$	A_B^1	S_B^1	$\mathcal{R}_H^2]$			
$[G_B^1$	A_B^1	S_B^1	G_R^3	$\mathcal{V}_R^3]$		
$[G_B^1$	A_B^1	S_B^1	$\mathcal{G}_R^3]$			
$[G_B^1$	A_B^1	$\mathcal{S}_B^1]$				
$[G_B^1$	A_B^1	$\mathcal{O}_S^2]$				

cota de profundidad = 3

