

Algoritmo con profundidad limitada (Depth-limited search - DLS)

Agenda

cota de profundidad = 3

$[\mathcal{B}] \leftarrow$ Estado inicial

$[G_B^1 \quad A_B^1 \quad S_B^1 \quad \cancel{H}_B^1]$

$[G_B^1 \quad A_B^1 \quad S_B^1 \quad R_H^2 \quad J_H^2 \quad \cancel{V}_H^2]$

$[G_B^1 \quad A_B^1 \quad S_B^1 \quad R_H^2 \quad \cancel{J}_H^2]$

$[G_B^1 \quad A_B^1 \quad S_B^1 \quad R_H^2 \quad \cancel{D}_J^3]$

$[G_B^1 \quad A_B^1 \quad S_B^1 \quad \cancel{R}_H^2]$

sacar()

